

# NAG Toolbox for MATLAB

## c06fk

### 1 Purpose

c06fk calculates the circular convolution or correlation of two real vectors of period  $n$  (using a work array for extra speed).

### 2 Syntax

```
[x, y, ifail] = c06fk(job, x, y, 'n', n)
```

### 3 Description

c06fk computes:

if **job** = 1, the discrete **convolution** of  $x$  and  $y$ , defined by

$$z_k = \sum_{j=0}^{n-1} x_j y_{k-j} = \sum_{j=0}^{n-1} x_{k-j} y_j;$$

if **job** = 2, the discrete **correlation** of  $x$  and  $y$  defined by

$$w_k = \sum_{j=0}^{n-1} x_j y_{k+j}.$$

Here  $x$  and  $y$  are real vectors, assumed to be periodic, with period  $n$ , i.e.,  $x_j = x_{j \pm n} = x_{j \pm 2n} = \dots$ ;  $z$  and  $w$  are then also periodic with period  $n$ .

**Note:** this usage of the terms ‘convolution’ and ‘correlation’ is taken from Brigham 1974. The term ‘convolution’ is sometimes used to denote both these computations.

If  $\hat{x}$ ,  $\hat{y}$ ,  $\hat{z}$  and  $\hat{w}$  are the discrete Fourier transforms of these sequences, i.e.,

$$\hat{x}_k = \frac{1}{\sqrt{n}} \sum_{j=0}^{n-1} x_j \times \exp\left(-i \frac{2\pi jk}{n}\right), \text{ etc.,}$$

then  $\hat{z}_k = \sqrt{n} \cdot \hat{x}_k \hat{y}_k$  and  $\hat{w}_k = \sqrt{n} \cdot \hat{x}_k \bar{\hat{y}}_k$  (the bar denoting complex conjugate).

This function calls the same auxiliary functions as c06fa and c06fb to compute discrete Fourier transforms, and there are some restrictions on the value of  $n$ .

### 4 References

Brigham E O 1974 *The Fast Fourier Transform* Prentice–Hall

### 5 Parameters

#### 5.1 Compulsory Input Parameters

1: **job** – int32 scalar

The computation to be performed.

**job** = 1

$$z_k = \sum_{j=0}^{n-1} x_j y_{k-j} \text{ (convolution);}$$

**job** = 2

$$w_k = \sum_{j=0}^{n-1} x_j y_{k+j} \text{ (correlation).}$$

*Constraint:* **job** = 1 or 2.

2: **x(n)** – **double array**

The elements of one period of the vector  $x$ . If **x** is declared with bounds  $(0 : \mathbf{n} - 1)$  in the (sub)program from which c06fk is called, then **x(j)** must contain  $x_j$ , for  $j = 0, 1, \dots, n - 1$ .

3: **y(n)** – **double array**

The elements of one period of the vector  $y$ . If **y** is declared with bounds  $(0 : \mathbf{n} - 1)$  in the (sub)program from which c06fk is called, then **y(j)** must contain  $y_j$ , for  $j = 0, 1, \dots, n - 1$ .

## 5.2 Optional Input Parameters

1: **n** – **int32 scalar**

*Default:* The dimension of the arrays **x**, **y**. (An error is raised if these dimensions are not equal.)

$n$ , the number of values in one period of the vectors **x** and **y**. The largest prime factor of **n** must not exceed 19, and the total number of prime factors of **n**, counting repetitions, must not exceed 20.

*Constraint:* **n** > 1.

## 5.3 Input Parameters Omitted from the MATLAB Interface

work

## 5.4 Output Parameters

1: **x(n)** – **double array**

The corresponding elements of the discrete convolution or correlation.

2: **y(n)** – **double array**

The discrete Fourier transform of the convolution or correlation returned in the array **x**; the transform is stored in Hermitian form, exactly as described in the document for c06fa.

3: **ifail** – **int32 scalar**

0 unless the function detects an error (see Section 6).

## 6 Error Indicators and Warnings

Errors or warnings detected by the function:

**ifail** = 1

At least one of the prime factors of **n** is greater than 19.

**ifail** = 2

**n** has more than 20 prime factors.

**ifail** = 3

On entry, **n**  $\leq$  1.

**ifail** = 4

On entry, **job**  $\neq$  1 or 2.

## 7 Accuracy

The results should be accurate to within a small multiple of the *machine precision*.

## 8 Further Comments

The time taken is approximately proportional to  $n \times \log n$ , but also depends on the factorization of  $n$ . c06fk is faster if the only prime factors of  $n$  are 2, 3 or 5; and fastest of all if  $n$  is a power of 2.

## 9 Example

```

job = int32(1);
x = [1;
     1;
     1;
     1;
     1;
     0;
     0;
     0;
     0];
y = [0.5;
     0.5;
     0.5;
     0.5;
     0;
     0;
     0;
     0;
     0];
[xOut, yOut, ifail] = c06fk(job, x, y)

xOut =
    0.5000
    1.0000
    1.5000
    2.0000
    2.0000
    1.5000
    1.0000
    0.5000
    0.0000
yOut =
    3.3333
   -1.0585
   -0.0082
    0.0833
    0.0667
   -0.0243
   -0.1443
   -0.0465
   -0.8882

```

```
ifail =  
      0
```

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